

## 4activeDR-Driving Robot

#### highly advanced system for computer controlled driving of cars & trucks

- ✓ drives the vehicle by operating the steering wheel, accelerator and brake pedal
  ✓ providing lateral and/or longitudinal closed-loop or open-loop operation modes
- to perform standard and customized test procedures with robotic precision

### providing the highest level of user friendliness

- very flexible and comfortable user interface
- highly performant robot control software
- modular actuator design and flexible application software

### precise - reliable - efficient

- designed for a fast installation into vehicles without changes to the car
- compact, lightweighted and ruggedized components each component < 10 kg
- only quick teach-in set-up no calibration required

# 4activeDR-Driving Robot

### steering actuator

	ADAS/ NCAP config.	High Dynamic config.
nominal load point	10 Nm @ 720 %sec	60 Nm @ 1280 %sec
max. speed	750 %sec	1700 %sec
max. torque	30 Nm	75 Nm
<ul><li>steering wheel diameter range</li><li>torque support on driver'side</li></ul>	- app. 377 – 405 mm   ☑ uncov ☑ hand	vered airbag area le bars for the driver

### throttle actuator

angle	90°max.	
torque	15 Nm (nom), 30 Nm (max)	
velocity	330 % max.	
✓ lays on pedal (free access to hu	man foot) 🔽 adjustable position	

### brake actuator

	ADAS/NCAP config.	High Dynamic config.
stroke	150 mm max.	150 mm max.
force	350 N max.	1.800 N max.
velocity	0.4 m/s max.	2.1 m/s max.
pneumatical brake redundancy	upon request	clamping attachment, no drills

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pneumatical brake redundancy upon request

### **Key extensions**

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- clutch + shift robot for manual transmission
- ✓ truck adapter set

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- driverless add-ons with brake redundancy
- keyboys for starting / stopping engine

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